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(%i1) kill(all);
(%o0) done

(%i1) depends([gamma,v1],r1);
(%o1) [Gamma(r1),v1(r1)]
```

1 Eq. (48)

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(%i2) E48: diff(gamma*m(r1), r1) = diff(1/gamma, r1);
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$$(E48) \quad m(r1) \left(\frac{d}{dr1} \Gamma \right) + \left(\frac{d}{dr1} m(r1) \right) \Gamma = - \frac{\frac{d}{dr1} \Gamma}{\Gamma^2}$$

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(%i3) gamma: (m(r1)-v1^2/c^2)^(-1/2);
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$$(gamma) \quad \frac{1}{\sqrt{m(r1) - \frac{v1^2}{c^2}}}$$

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(%i4) ev(E48);
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$$(\%o4) \quad m(r1) \left(\frac{d}{dr1} \frac{1}{\sqrt{m(r1) - \frac{v1^2}{c^2}}} \right) + \frac{\frac{d}{dr1} m(r1)}{\sqrt{m(r1) - \frac{v1^2}{c^2}}} = - \left(m(r1) - \frac{v1^2}{c^2} \right) \left(\frac{d}{dr1} \frac{1}{\sqrt{m(r1) - \frac{v1^2}{c^2}}} \right)$$

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(%i5) E48a: ev(E48, diff);
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$$(E48a) \quad \frac{\frac{d}{dr1} m(r1)}{\sqrt{m(r1) - \frac{v1^2}{c^2}}} - \frac{m(r1) \left(\frac{d}{dr1} m(r1) - \frac{2 v1 \left(\frac{d}{dr1} v1 \right)}{c^2} \right)}{2 \left(m(r1) - \frac{v1^2}{c^2} \right)^{3/2}} = \frac{\frac{d}{dr1} m(r1) - \frac{2 v1 \left(\frac{d}{dr1} v1 \right)}{c^2}}{2 \sqrt{m(r1) - \frac{v1^2}{c^2}}}$$

re-insert gamma

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(%i6) E48b: ratsubst(gamma, gamma, E48a);
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$$(E48b) \quad \frac{2 \gamma^3 m(r1) v1 \left(\frac{d}{dr1} v1 \right) + (2 \gamma c^2 - \gamma^3 c^2 m(r1)) \left(\frac{d}{dr1} m(r1) \right)}{2 c^2} = - \frac{2 \gamma v1 \left(\frac{d}{dr1} v1 \right) - \gamma c^2 \left(\frac{d}{dr1} m(r1) \right)}{2 c^2}$$

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(%i7) E48c: expand(E48b/'gamma*c^4);
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$$(E48c) \quad 2 \gamma^2 c^2 m(r1) v1 \left(\frac{d}{dr1} v1 \right) - \gamma^2 c^4 m(r1) \left(\frac{d}{dr1} m(r1) \right) + 2 c^4 \left(\frac{d}{dr1} m(r1) \right) = c^4 \left(\frac{d}{dr1} m(r1) \right) - 2 c^2 v1 \left(\frac{d}{dr1} v1 \right)$$

2 Final form of (48) or (57), resp.

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(%i8) E48d: expand(E48c/c^4);
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$$(E48d) \quad \frac{2 \gamma^2 m(r1) v1 \left(\frac{d}{dr1} v1 \right)}{c^2} - \gamma^2 m(r1) \left(\frac{d}{dr1} m(r1) \right) + 2 \left(\frac{d}{dr1} m(r1) \right) = \frac{d}{dr1} m(r1) - \frac{2 v1 \left(\frac{d}{dr1} v1 \right)}{c^2}$$

3 General solution of (57) (transcendental eq.)

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(%i9) ode2(E48d, m(r1), r1);
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$$(\%o9) \quad - \frac{2 c^2 \log(\gamma^2 m(r1) + 1) - \gamma^2 c^2 m(r1)}{2 \gamma^2 v1} = \int \frac{d}{dr1} v1 dr1 + \%c$$

4 Solution in plane polar coordinates

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(%i10) v1: sqrt(r_d^2+r1^2*phi_d^2);
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$$(v1) \quad \sqrt{r_d^2 + \varphi_d^2 r1^2}$$

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(%i11) E48e: ev(E48d, diff);
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$$(E48e) \quad -\gamma^2 m(r1) \left(\frac{d}{dr1} m(r1) \right) + 2 \left(\frac{d}{dr1} m(r1) \right) + \frac{2 \gamma^2 \varphi_d^2 r1 m(r1)}{c^2} = \frac{d}{dr1} m(r1) - \frac{2 \varphi_d^2 r1}{c^2}$$

```
(%i12) E48f: ode2(E48e, m(r1), r1);
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$$(E48f) \quad -\frac{2c^2 \log(\gamma^2 m(r1) + 1) - \gamma^2 c^2 m(r1)}{2\gamma^2 \varphi_d^2} = \frac{r1^2}{2} + \%c$$

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(%i13) E48g: expand(E48f/c^2*2*phi_d^2);
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$$(E48g) \quad m(r1) - \frac{2 \log(\gamma^2 m(r1) + 1)}{\gamma^2} = \frac{\varphi_d^2 r1^2}{c^2} + \frac{2 \%c \varphi_d^2}{c^2}$$

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(%i14) A1: factor(rhs(E48g));
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$$(A1) \quad \frac{\varphi_d^2 (r1^2 + 2 \%c)}{c^2}$$

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(%i15) E48h: lhs(E48g) = A1;
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$$(E48h) \quad m(r1) - \frac{2 \log(\gamma^2 m(r1) + 1)}{\gamma^2} = \frac{\varphi_d^2 (r1^2 + 2 \%c)}{c^2}$$

4.1 Replacement of %c by C

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(%i16) E48i: expand(ratsubst(C, 2*%c/c^2, E48h));
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$$(E48i) \quad m(r1) - \frac{2 \log(\gamma^2 m(r1) + 1)}{\gamma^2} = \frac{\varphi_d^2 r1^2}{c^2} + C \varphi_d^2$$

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(%i17) E48j: lhs(E48i) = factor(rhs(E48i));
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$$(E48j) \quad m(r1) - \frac{2 \log(\gamma^2 m(r1) + 1)}{\gamma^2} = \frac{\varphi_d^2 (r1^2 + C c^2)}{c^2}$$

4.2 Determination of %c from m(r10)=m0

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(%i18) E48j: ratsubst(m_0, m(r1), E48i);
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$$(E48j) \quad -\frac{2 \log(\gamma^2 m_0 + 1) - \gamma^2 m_0}{\gamma^2} = \frac{\varphi_d^2 r1^2 + C c^2 \varphi_d^2}{c^2}$$

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(%i19) E48k: ratsubst(r_10, r1, E48j);
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$$(E48k) \quad -\frac{2 \log(\gamma^2 m_0 + 1) - \gamma^2 m_0}{\gamma^2} = \frac{\varphi_d^2 (r_{10}^2 + C c^2)}{c^2}$$

```
(%i20) E48l: ratsubst(phi_d0, phi_d, E48k);
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$$(E48l) \quad -\frac{2 \log(\gamma^2 m_0 + 1) - \gamma^2 m_0}{\gamma^2} = \frac{\phi_{d0}^2 r_{10}^2 + C c^2 \phi_{d0}^2}{c^2}$$

```
(%i21) E48m: ratsubst(%gamma_0, %gamma, E48l);
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$$(E48m) \quad -\frac{2 \log(\gamma_0^2 m_0 + 1) - \gamma_0^2 m_0}{\gamma_0^2} = \frac{\phi_{d0}^2 r_{10}^2 + C c^2 \phi_{d0}^2}{c^2}$$

```
(%i22) expand(solve(E48m, C));
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$$(\%o22) \quad [C = -\frac{r_{10}^2}{c^2} - \frac{2 \log(\gamma_0^2 m_0 + 1)}{\gamma_0^2 \phi_{d0}^2} + \frac{m_0}{\phi_{d0}^2}]$$

5 Inertial system

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(%i23) v1: r1_d;
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$$(v1) \quad r1_d$$

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(%i24) E48e: ev(E48d, diff);
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$$(E48e) \quad 2 \left(\frac{d}{d r1} m(r1) \right) - \gamma^2 m(r1) \left(\frac{d}{d r1} m(r1) \right) = \frac{d}{d r1} m(r1)$$

```
(%i25) solve(E48e, m(r1));
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$$(\%o25) \quad [m(r1) = \frac{1}{\gamma^2}, \frac{d}{d r1} m(r1) = 0]$$

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(%i26) E48f: ode2(E48e, m(r1), r1);
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$$(E48f) \quad m(r1) = \%c$$